

QUALITATIVE BEHAVIOR OF A SECOND ORDER DELAY DYNAMIC EQUATIONS

Dr. P.Mohankumar¹, A.K. Bhuvaneshwari²

¹Professor of Mathematics

²Asst.Professor of Mathematics

Aarupadaiveedu Institute of Techonology, Vinayaka Missions University,
Paiyanoor, Kancheepuram Dist- 603104 , Tamilnadu, India

Abstract : In this paper we study the qualitative behavior of delay dynamic equation of the form

$$\left(\frac{1}{r(t)} y^\Delta(t)\right)^\Delta + p(t)y(\tau(t)) = 0, t \in T \dots\dots(1)$$

using Ricatti substitution method.

1. INTRODUCTION

The theory of time scales, which has recently established a lot of attention, was introduced by Hilger in his Ph.D. Thesis in 1988 in order to combine continuous and discrete analysis. A time scale T is an arbitrary closed subset of the reals, and the cases when this time scale is equal to the reals or to the integers represent the usual theories of differential and of difference equations. Many other remarkable time scales exist, and they give rise to plenty of applications, among them the study of population dynamic models which are discrete in season and may follow a difference scheme with variable step-size or often model by continuous dynamic systems die out, say in winter, while their eggs are incubating or hidden, and then in season again, hatching gives rise to a non overlapping population .It not only unify the theories of differential equations and difference equations but also it extends these classical cases to cases “in between”, for example, to the so-called q -difference equations when

$$T = qN_0 = \{t \in N_0, \quad q > 1\}$$

which has important applications in quantum theory and can be applied on various types of time scales like

$T=hN$, $T = N_2$, and $T = T_n$ the space of the harmonic numbers.

Consider the second order delay dynamic equation(1)

$$\left(\frac{1}{r(t)} y^\Delta(t)\right)^\Delta + p(t)y(\tau(t)) = 0$$

Where $p(t)$, $r(t)$ are positive right dense continous functions defined on T and $\tau : T \rightarrow T$ satisfies $\tau(t) \leq t$ for every $t \in T$ and $\lim_{t \rightarrow \infty} \tau(t) = \infty$

A solution $y(t)$ of equation (1) is said to be oscillatory if it is neither eventually positive nor eventually negative, that is if for every $b > a$ there exists $t > b$ such that $y(t)=0$ or $y(t)y(\sigma(t)) < 0$; otherwise it is called nonoscillatory. Since we are interested in qualitative behavior of solutions, we will suppose that the time scale T under considerations is not

bounded above and therefore the time scale is in the form $[t_0, \infty)_T = [t_0, \infty) \cap T$.

Note that if $T=N$ we have

$$\sigma(n) = n + 1$$

$$\mu(n) = 1$$

$$y^\Delta(n) = \Delta y(n)$$

then (1) becomes,

$$\Delta \left(\frac{1}{r(n)} \Delta y(n) \right) + p(n)y(\tau(n)) = 0, \quad n \in N$$

If $T=R$ we have

$$\sigma(t) = t$$

$$\mu(t) = 0$$

$$f^\Delta(t) = f'(t).$$

then equation (1.) becomes

$$\left(\frac{1}{r(t)} y'(t)\right)' + p(t)y(\tau(t)) = 0$$

If $T = hN$, $h > 0$, we have

$$\sigma(t) = t + h$$

$$\mu(t) = h$$

$$y^\Delta(t) = \Delta_h(t) = \frac{y(t+h) - y(t)}{h}$$

then equation (1) becomes

$$\Delta_h \left(\frac{1}{r(t)} \Delta_h(y(t)) \right) + p(t)y(\tau(t)) = 0$$

MAIN RESULT

Theorem 1.

Assume that

(i) $M(t) = \int_{t_0}^t r(s) \Delta s \rightarrow \infty$ as $t \rightarrow \infty$

(ii) $\tau^\Delta(t) \geq 0$

(iii) $\int \left(M(\tau(t))p(t) - \frac{r(\tau(t))\tau^\Delta(t)}{4M(\tau(t))} \right) \Delta t = \infty$ Then

(1) is oscillatory.

Proof

Let $y(t)$ be a non oscillatory solution of (1). Without loss of generality we may assume that $y(t) > 0$ and $y(\tau(t)) > 0$ for $t \geq t_1$

From (1) we have $\left(\frac{1}{r(t)} y^\Delta(t)\right)^\Delta < 0$

This implies that (from (2)) $\left(\frac{1}{r(t)} y^\Delta(t)\right) > 0$

Now make the Ricatti substitution

$$V(t) = \frac{M(\tau(t))}{y(\tau(t))} \left(\frac{y^\Delta(t)}{r(t)}\right)$$

Then $V(t) > 0$. Now

$$V^\Delta(t) = \left(\frac{M(\tau(t))}{y(\tau(t))}\right) \left(\frac{y^\Delta(t)}{r(t)}\right)^\Delta + \left(\frac{M(\tau(t))}{y(\tau(t))}\right)^\Delta \left(\frac{y^\Delta(t)}{r(t)}\right)^\sigma$$

$$= \left(\frac{M(\tau(t))}{y(\tau(t))}\right) \left(\frac{y^\Delta(t)}{r(t)}\right)^\Delta + \left(\frac{y^\Delta(t)}{r(t)}\right)^\sigma \left(\frac{y(\tau(t))r(\tau(t))\tau^\Delta(t) - M(\tau(t))y^\Delta(\tau(t))\tau^\Delta(t)}{y(\tau(t))y^\sigma(\tau(t))}\right)$$

$$= -M(\tau(t))p(t) + \frac{r(\tau(t))\tau^\Delta(t)}{M(\tau(t))} V^\sigma(t)$$

$$- V^\sigma(t) \frac{y^\Delta(\tau(t))}{r(\tau(t))} \times \frac{r(\tau(t))\tau^\Delta(t)}{y(\tau(t))}$$

Since $\left(\frac{y^\Delta(t)}{r(t)}\right)$ is decreasing, $\frac{y^\Delta(\tau(t))}{r(\tau(t))} \geq \frac{y^\Delta(t)}{r(t)}$

$$\therefore V^\Delta(t) \leq \frac{r(\tau(t))\tau^\Delta(t)}{M(\tau(t))} V^\sigma(t) - \frac{r(\tau(t))\tau^\Delta(t)}{y(\tau(t))} \frac{y^\Delta(t)}{r(t)} V^\sigma(t) - M(\tau(t))p(t).$$

$$= \frac{r(\tau(t))\tau^\Delta(t)}{M(\tau(t))} (V^\sigma(t) - (V^\sigma(t))^2) - M(\tau(t))p(t)$$

As the polynomial $P(V) = V^\sigma - (V^\sigma)^2 \leq \frac{1}{4}$

$$V^\Delta(t) \leq \frac{r(\tau(t))\tau^\Delta(t)}{4M(\tau(t))} - M(\tau(t))p(t)$$

Integrating from t_1 to t we get

$$V(t) \leq V(t_1) - \int_{t_1}^t \left(M(\tau(s))p(s) - \frac{r(\tau(s))\tau^\Delta(s)}{4M(\tau(s))} \right) \Delta s$$

Letting $t \rightarrow \infty$ $V(t) \rightarrow -\infty$

Which is a contradiction and hence the result.

Corollary

Assume that (i) and (ii) are satisfied and if

$$\liminf_{t \rightarrow \infty} \frac{M^2(t)p(t)}{r(t)} > \frac{1}{4}$$

then the equation $\left(\frac{1}{r(t)} y^\Delta(t)\right)^\Delta + p(t)y(t) = 0$

is oscillatory.

Proof

Put $\tau(t) = t$ in

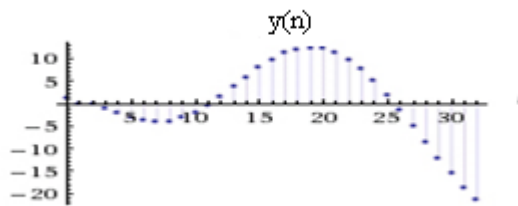
$$\int_{t_1}^{\infty} \left(M(\tau(t))p(t) - \frac{r(\tau(t))\tau^\Delta(t)}{4M(\tau(t))} \right) \Delta t = \infty$$

We get the result.

Example

Consider the dynamic equation of the form

$$\left(\frac{1}{t}\right)(y(t))^{\Delta\Delta} + \frac{1}{t^2} y(t-1) = 0, \quad t \in [1, \infty)_T \dots\dots\dots(2)$$



Hence every solution of equation (2) is oscillatory.

REFERENCES

1. M. Bohner and A. Peterson, Dynamic Equations on Time Scales, An Introduction with Applications, Birkhuser, Boston, 2001.
2. R. P. Agarwal, M. Bohner and A. Peterson, Dynamic equations on time scales: A survey. J. Comp. Appl. Math., Special issue on dynamic equations on time scales, edited by R.P. Agarwal, M. Bohner and D.O'Regan (Preprint in Ulmer Seminare 5), 141 (2002), 1–26,.
3. M. Huang and W. Feng, Oscillation for forced second order nonlinear dynamic equations on time scales, Elect. J. Diff. Eqn., 145 (2005), 1–8.
4. S. H. Saker, Oscillation of second order nonlinear neutral delay dynamic equations, J. Comp. Appl. Math., 187(2006), 123–141.
5. S. R. Grace, R. Agarwal, M. Bohner and D. O'Regan, Oscillation of second order strongly superlinear and strongly sublinear dynamic equations, Comm. Nonl. Sci Num. Sim., 14 (2009), 3463–3471.
6. P. Mohankumar and A. Ramesh, Oscillatory Behaviour Of The Solution Of The Third Order Nonlinear Neutral Delay Difference Equation, International Journal of Engineering Research & Technology (IJERT) ISSN: 2278-0181 Vol. 2 Issue 7, no. 1164-1168 July – 2013
7. B. Selvaraj, P. Mohankumar and A. Ramesh, On The Oscillatory Behavior of The Solutions to Second Order Nonlinear Difference Equations, International Journal of Mathematics and Statistics Invention (IJMSI) E-ISSN: 2321 – 4767 P-ISSN: 2321 - 4759 Volume 1 Issue 1 || Aug. 2013 || PP-19-21